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P00407	Clustering Wear Particle Using Computer Vision and SOM System	WA1
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P00325	Predictive Risk Assessment Using Cooperation Concept for Collision Avoidance of Side Crash in Autonomous Lane Change Systems	WA2
P00326	Vehicle Side Slip Angle Estimation Using Low-cost GPS/IMU	WA2
P00327	Vision-based Autonomous Indoor Valet Parking System	WA2
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P00295	Ensemble Tracking with Deep Reinforcement Learning	WA3
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P00392	Development of the Wearable Walking Robot for Spinal Cord Injury, RoboWear10	WA4
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P00317	Development of Robotic Catheter Control Systems for Master-Slave Tele-operative Arrhythmia Ablation in Asan Medical Center	WA5
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P00036	Twin-motor System Using a Data-driven Dual-rate Control	WA6
P00105	Primal Formulation of Parallel Model Predictive Control	WA6
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P00218	Continuous-time I-PD Gain Tuning Based on VRFT Using Closed-loop Step Response Data	WA6
P00344	Robust Control of Uncertain Robot Manipulator with a Momentum-based Disturbance Observer	WA6
P00405	Practicality and Performance Improvement of Time-delay Control	WA6
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P00043	Global consensus of heterogeneous agents with input saturation	WA7
P00085	A New Bearing-Only Navigation Law	WA7
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P00193	Consensus of linear time-invariant multi-agent system over multilayer network	WA7
P00395	Study on Lock-in Thermography using an inverse dynamic system design	WA7
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P00290	Sensor Security Index for Control Systems	WA8
P00402	Sensor Failure Detection, Identification and Accommodation Using Neural Network and Fuzzy Voter	WA8
P00161	Supervision of industrial manipulators using ANFIS system	WA8
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